

| Symbols (Terminals No.) | Wiring Color | Terminal Description | Condition | STD Voltage (V) |
| :---: | :---: | :---: | :---: | :---: |
| ST2 (H14-5) - GND1 (H14-1) | Y-W-B | Starter signal | Power switch ON (READY) | 9 to 14 |
| IGSW (H14-7) - | O-W-B | IG signal | Power switch ON (IG) | 9 to 14 |
| BATT (H15-6) - GND1 (H14-1) | Y - W-B | Auxiliary battery (for measuring the battery voltage and for the HV control ECU memory) | Always | 9 to 14 |
| +B1 (H16-7) - GND1 (H14-1) | L-W-B | Power source of HV control ECU | Power switch ON (IG) | 9 to 14 |
| +B2 (H16-6) - GND1 (H14-1) | L-W-B | Power source of HV control ECU | Power switch ON (IG) | 9 to 14 |
| $\begin{gathered} \text { MREL (H16-4) - } \\ \text { GND1 (H14-1) } \end{gathered}$ | O-W-B | Main relay | Power switch ON (IG) | 9 to 14 |
| $\begin{gathered} \text { CANH (H14-8) - } \\ \text { GND1 (H14-1) } \end{gathered}$ | B - W-B | HIGH-level CAN bus line | Power switch ON (IG) | Pulse generation (see waveform 1) |
| CANL (H14-9) - | W-W-B | LOW-level CAN bus line | Power switch ON (IG) | Pulse generation (see waveform 2) |
| $\begin{aligned} & \text { NEO (H16-12) - } \\ & \text { GND1 (H14-1) } \end{aligned}$ | LG-W-B | Engine speed signal | Engine running | Pulse generation (see waveform 3) |
| GO (H16-13) - GND1 (H14-1) | Y - W-B | G signal | Engine running | Pulse generation (see waveform 4) |
| $\text { SPDI (H14-19) - } \quad \text { GND1 (H14-1) }$ | V-W-B | Vehicle speed signal | Driving at approximately 12 mph ( $20 \mathrm{~km} / \mathrm{h}$ ) | Pulse generation (see waveform 5) |
| $\begin{aligned} & \text { VPA1 (H16-26) - } \\ & \text { EP1 (H16-27) } \end{aligned}$ | L-B | Accelerator pedal position sensor (for the HV system) | Power switch ON (IG), accelerator pedal released | 0.5 to 1.1 |
| $\begin{aligned} & \text { VPA1 (H16-26) - } \\ & \text { EP1 (H16-27) } \end{aligned}$ | L-B | Accelerator pedal position sensor (for the HV system) | Power switch ON (IG), engine stopped in P position, accelerator pedal fully depressed | 2.6 to 4.5 |
| $\begin{aligned} & \text { VPA2 (H16-34) - } \\ & \text { EP2 (H16-35) } \end{aligned}$ | W-R | Accelerator pedal position sensor (for the sensor malfunction detection) | Power switch ON (IG),accelerator pedal fully depressed | 1.2 to 2.0 |
| $\begin{aligned} & \text { VPA2 (H16-34) - } \\ & \text { EP2 (H16-35) } \end{aligned}$ | W-R | Accelerator pedal position sensor (for the sensor malfunction detection) | Power switch ON (IG), engine stopped in P position, accelerator pedal released | 3.4 to 5.3 |
| $\begin{aligned} & \text { VCP1 (H16-25) - } \\ & \text { EP1 (H16-27) } \end{aligned}$ | Y - B | Power source of accelerator pedal position sensor (for VPA1) | Power switch ON (IG) | 4.5 to 5.5 |

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| $\text { VCP2 (H16-33) - } \quad \text { EP2 (H16-35) }$ | $G-R$ | Power source of accelerator pedal position sensor (for VPA2) | Power switch ON (IG) | 4.5 to 5.5 |
| $\begin{aligned} & \hline \text { VSX1 (H14-25) - } \\ & \text { E2X1 (H14-15) } \end{aligned}$ | $B-R$ | Shift position sensor (main) | Power switch ON (IG), selector lever home position | 2.0 to 3.0 |
| $\begin{array}{\|l} \hline \text { VSX1 (H14-25) - } \\ \text { E2X1 (H14-15) } \end{array}$ | $B-R$ | Shift position sensor (main) | Power switch ON (IG), selector lever moved to R position | 4.0 to 4.8 |
| $\begin{aligned} & \text { VSX1 (H14-25) - } \\ & \text { E2X1 (H14-15) } \end{aligned}$ | $B-R$ | Shift position sensor (main) | Power switch ON (IG), selector lever moved to B or D position | 0.2 to 1.0 |
| $\begin{aligned} & \text { VSX2 (H14-24) - } \\ & \text { E2X2 (H14-14) } \end{aligned}$ | L-Y | Shift position sensor (sub) | Power switch ON (IG), selector lever home position | 2.0 to 3.0 |
| $\begin{array}{r} \text { VSX2 (H14-24) - } \\ \text { E2X2 (H14-14) } \end{array}$ | $L-Y$ | Shift position sensor (sub) | Power switch ON (IG), selector lever moved to $R$ position | 4.0 to 4.8 |
| $\begin{aligned} & \text { VSX2 (H14-24) - } \\ & \text { E2X2 (H14-14) } \end{aligned}$ | $L-Y$ | Shift position sensor (sub) | Power switch ON (IG), selector lever moved to B or D position | 0.2 to 1.0 |
| $\begin{aligned} & \mathrm{VCX1}(\mathrm{H} 14-17)- \\ & \mathrm{E} 2 \mathrm{X} 1(\mathrm{H} 14-15) \end{aligned}$ | W-R | Power source of shift position sensor (for VSX1) | Power switch ON (IG) | 4.5 to 5.5 |
| VCX2 (H14-16) - | $\mathrm{G}-\mathrm{Y}$ | Power source of shift position sensor (for VSX2) | Power switch ON (IG) | 4.5 to 5.5 |
| $\begin{array}{\|l\|} \hline \text { VSX3 (H14-23) - } \\ \text { GND1 (H14-1) } \end{array}$ | $B R-W-B$ | Select position sensor (main) | Power switch ON (IG), selector lever home position | 0.5 to 2.0 |
| $\begin{array}{\|l} \hline \text { VSX3 (H14-23) - } \\ \text { GND1 (H14-1) } \end{array}$ | $B R-W-B$ | Select position sensor (main) | Power switch ON (IG), selector lever moved to R, N or D position | 3.0 to 4.85 |
| $\begin{array}{\|l\|} \hline \text { VSX4 (H14-30) - } \\ \text { GND1 (H14-1) } \end{array}$ | SB - W-B | Select position sensor (sub) | Power switch ON (IG), selector lever home position | 0.5 to 2.0 |
| $\begin{array}{r} \text { VSX4 (H14-30) - } \\ \text { GND1 (H14-1) } \end{array}$ | SB-W-B | Select position sensor (sub) | Power switch ON (IG), selector lever moved to R, N or D position | 3.0 to 4.85 |
| VCX3 (H14-21) - | W-W-B | Power source of select position sensor (for VSX3) | Power switch ON (IG) | 9 to 14 |
| $\text { VCX4 (H14-31) - } \quad \text { GND1 (H14-1) }$ | P - W-B | Power source of select position sensor (for VSX4) | Power switch ON (IG) | 9 to 14 |
| $\begin{aligned} & \text { NODD (H16-24) - } \\ & \text { GND1 (H14-1) } \end{aligned}$ | $\mathrm{V}-\mathrm{W}-\mathrm{B}$ | DC/DC movement monitor or stop request signal | When converter is in normal operation | 5 to 7 |
| NODD (H16-24) - <br> GND1 (H14-1) | $\mathrm{V}-\mathrm{W}-\mathrm{B}$ | DC/DC movement monitor or stop request signal | When converter is improper | 2 to 4 |
| $\begin{aligned} & \text { NODD (H16-24) - } \\ & \text { GND1 (H14-1) } \end{aligned}$ | V - W-B | DC/DC movement monitor or stop request signal | When converter is required to stop | 0.1 to 0.5 |
| $\text { VLO (H16-31) - } \text { GND1 (H14-1) }$ | L-W-B | Two-stage selector signal | Converter switching to 14 V output | 13 to 14 |
| $\text { VLO (H16-31) - }{ }_{\text {GND1 (H14-1) }}$ | $\mathrm{L}-\mathrm{W}-\mathrm{B}$ | Two-stage selector signal | Converter switching to 13.5 V output | Below 0.5 |
| TC (H14-6) - GND1 (H14-1) | P - W-B | Terminal TC of DLC3 | Power switch ON (IG) | 9 to 14 |
| STP (H15-3) - GND1 (H14-1) | L-W-B | Stop lamp switch | Brake pedal depressed | 9 to 14 |
| STP (H15-3) - GND1 (H14-1) | L-W-B | Stop lamp switch | Brake pedal released | 2 to 3 |
| $\begin{array}{\|l\|} \hline \text { ABFS (H14-20) - } \\ \text { GND1 (H14-1) } \end{array}$ | L-W-B | Airbag deployment signal | Power switch ON (READY) (2 seconds after ACC ON) | Pulse generation (see waveform 6 to 8) |
| AS1 (H16-15) - | Y - W | Circuit breaker sensor No. 1 | Satellite signal system normal | 2.5 to 2.9 |
| ILK (H15-1) - GND1 (H14-1) | $\mathrm{V}-\mathrm{W}-\mathrm{B}$ | Interlock switch | Power switch ON (IG), inverter cover and service plug grip installed normally | Below 1 |


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| ILK (H15-1) - GND1 (H14-1) | V-W-B | Interlock switch | Power switch ON (IG), inverter cover or service plug grip detached | 9 to 14 |
| $\begin{array}{\|c\|} \hline \text { CON1 (H16-1) - } \\ \text { GND1 (H14-1) } \end{array}$ | R - W-B | System main relay No. 1 | Power switch OFF to ON (READY) | Pulse generation (see waveform 9) |
| CON2 (H16-2) - | G-W-B | System main relay No. 2 | Power switch OFF to ON (READY) | Pulse generation (see waveform 9) |
| $\text { CON3 (H16-3) - } \quad \text { GND1 (H14-1) }$ | Y - W-B | System main relay No. 3 | Power switch OFF to ON (READY) | Pulse generation (see waveform 9) |
| VH (H15-26) - GINV (H15-23) | Y - W-B | Inverter condenser voltage monitor | Power switch ON (READY) | 1.6 to 3.8 |
| $\begin{aligned} & \text { GUU (H15-15) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | B - Y | Generator switch U signal | Power switch ON (IG) | Pulse generation (see waveform 10) |
| $\begin{aligned} & \text { GVU (H15-14) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | G - Y | Generator switch V signal | Power switch ON (IG) | Pulse generation (see waveform 10) |
| $\begin{array}{\|l\|} \hline \text { GWU (H15-13) - } \\ \text { GINV (H15-23) } \\ \hline \end{array}$ | Y-Y | Generator switch W signal | Power switch ON (IG) | Pulse generation (see waveform 10) |
| $\begin{aligned} & \text { GIVA (H15-34) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | W-Y | Generator V phase current | Power switch ON (IG) | Approximately 0 |
| GIVB (H15-33) - $\quad$ GINV (H15-23) | B - Y | Generator V phase current | Power switch ON (IG) | Approximately 0 |
| $\begin{aligned} & \text { GIWA (H15-32) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | R-Y | Generator W phase current | Power switch ON (IG) | Approximately 0 |
| GIWB (H15-31) - <br> GINV (H15-23) | G - Y | Generator W phase current | Power switch ON (IG) | Approximately 0 |
| $\begin{aligned} & \text { GIVT (H15-27) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | W-Y | Generator inverter temperature sensor | Power switch ON (IG) | 2 to 4.5 |
| $\begin{aligned} & \text { GSDN (H15-16) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | R - W-B | Generator shutdown signal | Power switch ON (READY), N position | 0.2 to 0.7 |
| $\begin{gathered} \hline \text { GSDN (H15-16) - } \\ \text { GINV (H15-23) } \end{gathered}$ | R - W-B | Generator shutdown signal | Power switch ON (READY), P position | 5.1 to 13.6 |
| $\begin{aligned} & \text { GFIV (H15-35) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | GR - W-B | Generator inverter fail signal | Power switch ON (IG), inverter normal | 5.4 to 7.4 |
| $\begin{aligned} & \text { GFIV (H15-35) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | GR - W-B | Generator inverter fail signal | Power switch ON (IG), inverter abnormal | 2 to 3 |
| $\begin{aligned} & \text { GRF (H17-27) - } \\ & \text { GRFG (H17-26) } \end{aligned}$ | B-W | Generator resolver signal | Generator resolver stopped or rotating | Pulse generation (see waveform 11, 12) |
| $\begin{gathered} \text { GSN (H17-22) - } \\ \text { GSNG (H17-21) } \end{gathered}$ | R-G | Generator resolver signal | Generator resolver stopped or rotating | Pulse generation (see waveform 11, 12) |
| $\begin{aligned} & \text { GCS (H17-23) - } \\ & \text { GCSG (H17-24) } \end{aligned}$ | Y - BR | Generator resolver signal | Generator resolver stopped or rotating | Pulse generation (see waveform 11, 12) |
| $\begin{aligned} & \text { OMT (H17-30) - } \\ & \text { OMTG (H17-29) } \end{aligned}$ | B - G | Motor temperature sensor No. 2 | Refer to DATA LIST on page 05-434 | - |
| MUU (H15-9) - GINV (H15-23) | B - Y | Motor switch U signal | Power switch ON (IG) | Pulse generation (see waveform 13) |
| $\begin{aligned} & \text { MVU (H15-10) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | W-Y | Motor switch V signal | Power switch ON (IG) | Pulse generation (see waveform 13) |
| $\begin{gathered} \text { MWU (H15-11) - } \\ \text { GINV (H15-23) } \end{gathered}$ | R-Y | Motor switch W signal | Power switch ON (IG) | Pulse generation (see waveform 13) |
| $\begin{aligned} & \text { MIVA (H15-30) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | G - Y | Motor V phase current | Power switch ON (IG) | Approximately 0 |
| $\begin{aligned} & \text { MIVB (H15-21) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | W-Y | Motor V phase current | Power switch ON (IG) | Approximately 0 |
| $\begin{gathered} \text { MIWA (H15-29) - } \\ \text { GINV (H15-23) } \end{gathered}$ | R-Y | Motor W phase current | Power switch ON (IG) | Approximately 0 |

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| MIWB (H15-20) - <br> GINV (H15-23) | $B-Y$ | Motor W phase current | Power switch ON (IG) | Approximately 0 |
| $\begin{array}{\|l\|} \hline \text { MIVT (H15-19) - } \\ \text { GINV (H15-23) } \end{array}$ | L-Y | Motor inverter temperature sensor | Power switch ON (IG) | 2 to 4.5 |
| $\begin{aligned} & \text { MSDN (H15-8) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | $\mathrm{G}-\mathrm{W}-\mathrm{B}$ | Motor shutdown signal | Power switch ON (READY), N position | 0.2 to 0.7 |
| $\begin{array}{\|l\|} \hline \text { MSDN (H15-8) - } \\ \operatorname{GINV}(H 15-23) \end{array}$ | $\mathrm{G}-\mathrm{W}-\mathrm{B}$ | Motor shutdown signal | Power switch ON (READY), P position | 5.1 to 13.6 |
| $\begin{aligned} & \text { OVH (H15-22) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | $B R-W-B$ | Motor inverter over voltage signal | Power switch ON (IG), inverter normal | 5.3 to 7.3 |
| $\begin{aligned} & \text { OVH (H15-22) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | $B R-W-B$ | Motor inverter over voltage signal | Power switch ON (IG), inverter abnormal | 1.9 to 2.9 |
| $\begin{aligned} & \text { MFIV (H15-18) - } \\ & \text { GINV (H15-23) } \end{aligned}$ | $\mathrm{G}-\mathrm{W}-\mathrm{B}$ | Motor inverter fail signal | Power switch ON (IG), inverter normal | 5.4 to 7.4 |
| $\begin{array}{\|l\|} \hline \text { MFIV (H15-18) - } \\ \text { GINV (H15-23) } \end{array}$ | $\mathrm{G}-\mathrm{W}-\mathrm{B}$ | Motor inverter fail signal | Power switch ON (IG), inverter abnormal | 2 to 3 |
| MRF (H17-34) - <br> MRFG (H17-33) | $L-P$ | Motor resolver signal | Motor resolver stopped or rotating | Pulse generation (see waveform 11, 12) |
| MSN (H17-20) - <br> MSNG (H17-19) | $\mathrm{G}-\mathrm{R}$ | Motor resolver signal | Motor resolver stopped or rotating | Pulse generation (see waveform 11, 12) |
| MCS (H17-32) - <br> MCSG (H17-31) | Y - BR | Motor resolver signal | Motor resolver stopped or rotating | Pulse generation (see waveform 11, 12) |
| MMT (H17-18) - <br> MMTG (H17-28) | $B-R$ | Motor temperature sensor No. 1 | Refer to DATA LIST on page 05-434 | - |
| VL (H16-30) - GCNV (H16-8) | Y - G | Boost converter input voltage | Power switch ON (READY) | 1.9 to 3.4 |
| OVL (H16-22) - | B - G | Boost converter over voltage signal | Power switch ON (IG), boost converter normal | 5.3 to 7.7 |
| $\begin{aligned} & \text { OVL (H16-22) - } \\ & \text { GCNV (H16-8) } \end{aligned}$ | B - G | Boost converter over voltage signal | Power switch ON (IG), boost converter abnormal | 1.9 to 3.0 |
| $\begin{aligned} & \mathrm{FCV}(\mathrm{H} 16-20)- \\ & \text { GCNV (H16-8) } \end{aligned}$ | W-G | Boost converter fail signal | Power switch ON (IG), boost converter normal | 5.3 to 7.7 |
| $\begin{array}{\|l\|} \hline \text { FCV (H16-20) - } \\ \text { GCNV (H16-8) } \end{array}$ | W-G | Boost converter fail signal | Power switch ON (IG), boost converter abnormal | 1.9 to 3.0 |
| CT (H16-21) - GCNV (H16-8) | R-G | Boost converter temperature sensor | Power switch ON (IG) | 2.0 to 4.5 |
| $\begin{aligned} & \text { CPWM (H16-10) - } \\ & \text { GCNV (H16-8) } \end{aligned}$ | B - G | Boost converter PWM switch signal | Power switch ON (READY), parking brake ON, D position, brake pedal and accelerator pedal depressed | Pulse generation (see waveform 14) |
| $\begin{array}{r} \text { CSDN (H16-9) - } \\ \text { GCNV (H16-8) } \end{array}$ | W-G | Boost converter shutdown signal | Power switch ON (IG) | 5.6 or higher |
| $\begin{aligned} & \text { CSDN (H16-9) - } \\ & \text { GCNV (H16-8) } \end{aligned}$ | W-G | Boost converter shutdown signal | Power switch ON (READY) | Below 0.7 |
| ST1- (H15-2) - GND1 (H14-1) | $\mathrm{G}-\mathrm{W}-\mathrm{B}$ | Stop lamp switch (opposite to STP) | Power switch ON (IG) and brake pedal depressed | Below 0.5 |
| ST1- (H15-2) - GND1 (H14-1) | $\mathrm{G}-\mathrm{W}-\mathrm{B}$ | Stop lamp switch (opposite to STP) | Power switch ON (IG) and brake pedal released | 9 to 14 |
| $\mathrm{CCS}(\mathrm{H} 14-13)-\quad \text { GND1 (H14-1) }$ | $\mathrm{V}-\mathrm{W}-\mathrm{B}$ | Cruise control switch | Cruise control system - Terminal of ECU - CCS terminal (see page 05-2690) | - |
| IMI (H14-18) - GND1 (H14-1) | W - W-B | Immobilizer communication | Immobilizer communicating | Pulse generation (see waveform 15) |
| IMO (H14-26) - GND1 (H14-1) | $\mathrm{R}-\mathrm{W}-\mathrm{B}$ | Immobilizer communication | Immobilizer communicating | Pulse generation (see waveform 15) |
| P1 (H15-17) - GND1 (H14-1) | Y - W-B | P position switch | Power switch ON (IG), P position switch ON | 3 to 5 |

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| P1 (H15-17) - GND1 (H14-1) | Y - W-B | P position switch | Power switch ON (IG), P position switch OFF | 7 to 12 |
| PCON (H17-9) - | LG - W-B | P position control signal | Power switch ON (IG) | Pulse generation (see waveform 16) |
| $\begin{aligned} & \text { PPOS (H17-10) - } \\ & \text { GND1 (H14-1) } \end{aligned}$ | W-W-B | P position signal | Power switch ON (IG) | Pulse generation (see waveform 16) |
| RDY (H14-28) - | $\mathrm{R}-\mathrm{W}-\mathrm{B}$ | READY control signal | Power switch ON (IG) | Pulse generation (see waveform 17) |
| RDY (H14-28) - | $\mathrm{R}-\mathrm{W}-\mathrm{B}$ | READY control signal | Power switch ON (READY) | Pulse generation (see waveform 18) |
| CLK (H16-17) - GND1 (H14-1) | $\mathrm{G}-\mathrm{W}-\mathrm{B}$ | A/C communication | Power switch ON (IG), A/C operating | Pulse generation (see waveform 19) |
| ITE (H16-14) - GND1 (H14-1) | Y - W-B | A/C communication | Power switch ON (IG), A/C operating | Pulse generation (see waveform 19) |
| ETI (H15-24) - GND1 (H14-1) | $\mathrm{R}-\mathrm{W}-\mathrm{B}$ | A/C communication | Power switch ON (IG), A/C operating | Pulse generation (see waveform 19) |
| STB (H15-25) - GND1 (H14-1) | W-W-B | A/C communication | Power switch ON (IG), A/C operating | Pulse generation (see waveform 19) |
| WP (H16-5) - GND1 (H14-1) | $\mathrm{O}-\mathrm{W}-\mathrm{B}$ | Water pump relay control | Power switch ON (IG), A/C operating | Below 2 |
| GND1 (H14-1) - Body ground | W-B - <br> Body ground | Ground | Always (resistance check) | Below $5 \Omega$ |
| GND2 (H14-4) - Body ground | W-B - <br> Body ground | Ground | Always (resistance check) | Below $5 \Omega$ |

## 1. Oscilloscope waveforms

HINT:
In the oscilloscope waveform samples, which are provided here for informational purposes. Noise and fluttering waveforms have been omitted.

(a) Waveform 1 (HIGH-level CAN bus line)

| Item | Contents |
| :---: | :---: |
| Terminal | CANH - GND1 |
| Equipment Setting | 1 V/Division, $2 \mu \mathrm{~s} /$ Division |
| Condition | Power switch ON (IG) |

HINT:
The waveform varies depending on the contents of communication.

(b) Waveform 2 (LOW-level CAN bus line)

| Item | Contents |
| :---: | :---: |
| Terminal | CANL - GND1 |
| Equipment Setting | 1 V/Division, $2 \mu$ s/Division |
| Condition | Power switch ON (IG) |

HINT:
The waveform varies depending on the contents of communication.

(c) Waveform 3 (engine speed signal)

| Item | Contents |
| :---: | :---: |
| Terminal | NEO - GND1 |
| Equipment Setting | 1 V/Division, 2 ms/Division |
| Condition | Engine idling |

HINT:
The pulse cycle becomes shorter as the engine speed increases.
(d) Waveform 4 (G signal)

| Item | Contents |
| :---: | :---: |
| Terminal | GO - GND1 |
| Equipment Setting | 2 V/Division, 20 ms/Division |
| Condition | Engine idling |

(e) Waveform 5 (vehicle speed signal)

| Item | Contents |
| :---: | :---: |
| Terminal | SPDI - GND1 |
| Equipment Setting | 2 V/Division, $20 \mathrm{~ms} /$ Division |
| Condition | Driving at approximately $20 \mathrm{~km} / \mathrm{h}(12 \mathrm{mph})$ |

HINT:
The higher the vehicle speed, the shorter the cycle and higher the voltage.
(f) Waveform 6 (airbag deployment signal)

| Item | Contents |
| :---: | :---: |
| Terminal | ABFS - GND1 |
| Equipment Setting | 1 V/Division, 500 ms/Division |
| Condition | Power switch ON (READY) (2 seconds after ACC ON) |
|  | Airbag system normal |

HINT:
The waveform on the left is repeated when the airbag system is normal.
(g) Waveform 7 (airbag deployment signal)

| Item | Contents |
| :---: | :---: |
| Terminal | ABFS - GND1 |
| Equipment Setting | 1 V/Division, 50 ms/Division |
| Condition | Power switch ON (READY) (2 seconds after ACC ON) |
|  | Airbag system abnormal |

HINT:
The waveform on the left is repeated when the airbag system is abnormal.

(j) Waveform 10 (generator switch U, V, and W signal)

| Item | Contents |
| :---: | :---: |
|  | $\mathrm{CH1}:$ GUU - GINV |
| Terminal | $\mathrm{CH} 2: \mathrm{GVU}-\mathrm{GINV}$ |
|  | $\mathrm{CH} 3:$ GWU - GINV |
| Equipment Setting | $10 \mathrm{~V} /$ Division, $20 \mu \mathrm{~s} /$ Division |
| Condition | Power switch ON (IG) |

## (k) Waveform 11 (generator or motor resolver)

| Item | Contents |
| :---: | :---: |
| Terminal | CH1: GRF - GRFG |
| (Generator Resolver) | CH2: GSN - GSNG |
|  | CH3: GCS - GCSG |
| Terminal | $\mathrm{CH} 1:$ MRF - MRFG |
| (Motor Resolver) | $\mathrm{CH} 2: \mathrm{MSN}-\mathrm{MSNG}$ |
|  | $\mathrm{CH3}: \mathrm{MCS}-\mathrm{MCSG}$ |
| Equipment Setting | $\mathrm{CH} 1: 10 \mathrm{~V} /$ Division, $1 \mathrm{~ms} /$ Division |
|  | $\mathrm{CH} 2,3: 5 \mathrm{~V} /$ Division, $1 \mathrm{~ms} /$ Division |
| Condition | Generator or motor stopped |

HINT:
The phases and the waveform height of the GSN and GCS, or the MSN and MCS change depending on the stopped position of rotor.

DIAGNOSTICS - HYBRID CONTROL SYSTEM

(I) Waveform 12 (generator or motor resolver)

| Item | Contents |
| :---: | :---: |
| Terminal | CH1: GRF - GRFG |
| (Generator Resolver) | CH2: GSN - GSNG |
|  | CH3: GCS - GCSG |
| Terminal | CH1: MRF - MRFG |
| (Motor Resolver) | $\mathrm{CH} 2:$ MSN - MSNG |
|  | $\mathrm{CH} 3: \mathrm{MCS}-\mathrm{MCSG}$ |
| Equipment Setting | $\mathrm{CH} 1: 10 \mathrm{~V} /$ Division, $1 \mathrm{~ms} /$ Division |
|  | $\mathrm{CH} 2,3: 5 \mathrm{~V} /$ Division, $1 \mathrm{~ms} /$ Division |
| Condition | Generator or motor stopped |

HINT:
Distance " A " in the diagram becomes shorter as the rotor speed increases.
(m) Waveform 13 (motor switch U, V, and W signal)

| Item | Contents |
| :---: | :---: |
|  | $\mathrm{CH} 1: \mathrm{MUU}-\mathrm{GINV}$ |
| Terminal | $\mathrm{CH} 2: \mathrm{MVU}-\mathrm{GINV}$ |
|  | $\mathrm{CH} 3: \mathrm{MWU}-\mathrm{GINV}$ |
| Equipment Setting | 10 V/Division, $50 ~ \mu \mathrm{~s} /$ Division |
| Condition | Power switch ON (IG) |

(n) Waveform 14 (boost converter PWM switch signal)

| Item | Contents |
| :---: | :---: |
| Terminal | CPWM -GCNV |
| Equipment Setting | 10 V/Division, $50 \mu \mathrm{~s} /$ Division |
| Condition | Power switch ON (READY), parking brake ON, D position, <br> brake pedal and accelerator pedal depressed |

(o) Waveform 15 (immobilizer communication)

| Item | Contents |
| :---: | :---: |
| Terminal | CH1: IMO - GND1 <br> $\mathrm{CH2}: \mathrm{IMI}-\mathrm{GND} 1$ |
| Equipment Setting | $5 \mathrm{~V} /$ Division, $200 \mathrm{~ms} /$ Division |
| Condition | Immobilizer communicating |


(p) Waveform 16 (P position control signal, P position signal)

| Item | Contents |
| :---: | :---: |
| Terminal | CH1: PCON - GND1 |
|  | CH2: PPOS - GND1 |
| Equipment Setting | 5 V/Division, $20 \mathrm{~ms} /$ Division |
| Condition | Power switch ON (IG) |

(q) Waveform 17 (READY control signal)

| Item | Contents |
| :---: | :---: |
| Terminal | RDY - GND1 |
| Equipment Setting | 2 V/Division, 20 ms/Division |
| Condition | Power switch ON (IG) |

(r) Waveform 18 (READY control signal)

| Item | Contents |
| :---: | :---: |
| Terminal | RDY - GND1 |
| Equipment Setting | 2V/Division, 20ms/Division |
| Condition | Power switch ON (READY) |

(s) Waveform 19 (A/C communication)

| Item | Contents |
| :---: | :---: |
|  | CH1: IGSW - GND1 |
| Terminal | CH2: ITE - GND1 |
|  | CH3: CLK - GND1 |
|  | CH4: ETI - GND1 |
|  | CH5: STB- GND1 |
| Equipment Setting | 10 V/Division, 50 ms/Division |
| Condition | Power switch ON (IG) and A/C operating |

